

**AMENDMENTS TO THE SPECIFICATION**

Please replace the title in its entirety with the following new title:

-- ILLUMINATION APPARATUS HAVING FRONT AND SIDE ILLUMINATION UNITS --

Please replace the paragraph beginning on page 11, line 23, with the following new paragraph:

-- From a plurality of portions of the back face of the ornamental plate 17, attaching legs 17a extend rearwardly. These attaching legs ~~17g~~ 17a are connected between the adjacent front lamp supporting portions 11b. --

Please replace the paragraph beginning on page 11, line 26, with the following new paragraph:

-- The translucent lens 18 includes a front lens portion 18a covering the right and left front lamps 12 and the ornamental plate 17, a left side lens portion 18b covering the left side lamp 15, and a right lens portion ~~18b~~ 18c covering the right side lamp 15, with these lens portions being formed together to construct a one-piece lens. As shown in Figs. 4 and 5, the translucent lens 18 is directly connected and supported to the frame 11. This direct connection can be realized in the following manner for example. That is, the translucent lens 18 is placed in abutment against the open peripheral edge of the frame 11, so that this translucent lens 18 acts as a cover for an entire opening 11h of the accommodating recess 11e of the frame 11. Then, under this condition, the peripheral edge of the translucent lens 18 is bonded by means of adhesive to the open peripheral edge of the frame 11. --

Please replace the paragraph beginning on page 13, line 11, with the following new paragraph:

-- The steering angle sensor 34 comprises e.g. a potentiometer. And, an operational portion of this potentiometer is operably coupled to a pitman arm 40 of a steering device (not shown) operably connecting a steering wheel 25 to a knuckle arm 40 of the right and left front wheels 1. In operation, this steering angle sensor 34 detects whether the right and left front wheels 1 have been laterally steered by an angle exceeding a preset minimum steering angle (e.g. 30 degrees), based on a pivoted angle of the pitman arm 40 relative to a reference position and detects also whether the steering direction of the front wheels 1 is to the left or to the right. And, these detection results are inputted to the controller 23. --

Please replace the paragraph beginning on page 13, line 21 with the following new paragraph:

-- The lift angle sensor 35 can also be a potentiometer. And, an operational portion of this potentiometer is operably coupled to the lift arm 6a. In operation, this ~~left~~ lift angle sensor 35 detects that the rotary plow 30 connected to the vehicle body 100 has been lowered to a work position and detects also that the plow has been elevated to a non-work position And, these detection results are inputted to the controller 23. --